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camera control\* and map

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[\[Abstract\]](#) [\[PDF Full-Text \(1520 KB\)\]](#) **IEEE CNF****2 A framework for robot control with active vision using a neural net based spatial representation***Sharma, R.; Srinivasa, N.;*Robotics and Automation, 1996. Proceedings., 1996 IEEE International Conf  
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*Ahuja, N.; Abbott, A.L.;*

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camera and map and position and direction

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**1 Mobile robot localization using a single image**

*Krotkov, E.;*

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*Natonek, E.; Baur, C.;*

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**3 A hard X-ray imaging polarimeter for balloon-borne astronomy**

*Austin, R.A.; Minamitani, T.; Ramsey, B.D.;*

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**4 A semi-autonomous sewer surveillance and inspection vehicle**

*Gooch, R.M.; Clarke, T.A.; Ellis, T.J.;*

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**5 Identification of pelagic eggs by image analysis**

*Qingmin Liao; Kacem Chehdi; Xinggang Lin; Yujin Zhang;*

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**6 Making a local map of indoor environments by swiveling a camera :  
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*Shigang Li; Kanbara, T.; Hayashi, A.;*

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*Kalkusch, M.; Lidy, T.; Knapp, N.; Reitmayr, G.; Kaufmann, H.; Schmalstieg,*  
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